

Chapter 5

* Two basic equations of the electrostatic model

$$\nabla \cdot \mathbf{E} = \frac{\rho_v}{\epsilon_0} \quad \nabla \times \mathbf{E} = 0$$

Electric flux 195

$$\nabla \cdot \mathbf{D} = \rho_v$$

$$\nabla \times \mathbf{E} = 0$$

if the medium linear and isotropic, we have relation " $\vec{D} = \epsilon \vec{E}$ "
↓
scalar

! Manis = Magnesia

* Electric Intensity defined in terms of force on a stationary charge

$$\vec{F}_e = q\mathbf{E} \text{ (N)}$$

electric force

* Magnetic flux density defined in terms of force experienced by a moving charge

$$\vec{F}_m = q\mathbf{u} \times \mathbf{B} \text{ (N)}$$

magnetic force magnetic flux density

velocity of moving charge (m/s)

B measured in webers per square meter (wb/m^2) or tesla (T)
 total magnetic force on a charge q is then $F = F_e + F_m$ ve lorentz's force equation olarak bilinir.

* Lorentz's force equation

$$F = q(E + u \times B) \text{ (N)}$$

$q(E + u \times B)$

Magnetic Flux density also called magnetic induction. $\rightarrow \Phi = BA \cos \theta$

charges in motion produce a current that, creates a magnetic field.

Fundamental postulates of Magnetostatics In Free Space

* Divergence of B vanishes

$$\nabla \cdot B = 0$$

* Curl of static B $\nearrow$ current density in nonmagnetic media

$$\nabla \times B = \mu_0 J \text{ (in nonmagnetic media)}$$

permeability of free space

$$\mu_0 = 4\pi \times 10^{-7} \text{ (H/m)}$$

* $\boxed{\nabla \cdot \mathbf{J} = 0}$ Divergence of the curl of any vector field is zero.

* There are no magnetic flow sources (no isolated magnetic charge)

$$\boxed{\oint_S \mathbf{B} \cdot d\mathbf{s} = 0}$$
 also expression for law of conservation of magnetic flux.

There are no magnetic flow sources, and the magnetic flux lines always close upon themselves

$$\oint_S (\nabla \times \mathbf{B}) \cdot d\mathbf{s} = \mu_0 \oint_V \mathbf{J} \cdot d\mathbf{s}$$

* $\boxed{\oint_C \mathbf{B} \cdot d\mathbf{l} = \mu_0 I}$ (in nonmagnetic media)

Postulates of Magnetostatics in nonmagnetic Media

Differential Form

Integral Form

$$\nabla \cdot \mathbf{B} = 0$$

$$\oint_S \mathbf{B} \cdot d\mathbf{s} = 0$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

$$\oint_C \mathbf{B} \cdot d\mathbf{l} = \mu_0 I$$

$$\nabla \times \mathbf{H} = \mathbf{J}, \mathbf{B} = \mu_0 \mathbf{H}, \mathbf{H} = \frac{\mathbf{B}}{\mu_0}$$

Vector Magnetic Potential

* Partial definition of vector magnetic potential $\mathbf{A}$

$$\mathbf{B} = \nabla \times \mathbf{A} \text{ (T)}$$

$$\nabla \times \nabla \times \mathbf{A} = \mu_0 \mathbf{J} \quad \text{"B'nin curl'u"}$$

$$\nabla \times \nabla \times \mathbf{A} = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

$$\nabla^2 \mathbf{A} = \nabla_x^2 \mathbf{A}_x + \nabla_y^2 \mathbf{A}_y + \nabla_z^2 \mathbf{A}_z$$

Bu durum diğer koordinat sistemleri içinde geçerlidir.

verify for cartesian coordinates.

$$\nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{j}$$

* coulomb condition for divergence of $\mathbf{A}$

$$\boxed{\nabla \cdot \mathbf{A} = 0}$$

→ This equation become

* $\boxed{\nabla^2 \mathbf{A} = \mu_0 \mathbf{j}}$ operator form of vector
Poisson's equation

→ Kartezyen koordinatlar

$$\nabla^2 A_x = -\mu_0 j_x$$

$$\nabla^2 A_y = -\mu_0 j_y$$

$$\nabla^2 A_z = -\mu_0 j_z$$

$$\left. \begin{array}{l} \nabla^2 A_x = -\mu_0 j_x \\ \nabla^2 A_y = -\mu_0 j_y \\ \nabla^2 A_z = -\mu_0 j_z \end{array} \right\} \equiv \nabla^2 V = -\frac{\rho_v}{\epsilon_0}$$

Scalar Poisson's equation in electrostatic

↓ denkleminin çözümü

Denkleminin çözümü

$$A_x = \frac{\mu_0}{4\pi} \int_{V'} \frac{j_x}{R} dV'$$

$$V = \frac{1}{4\pi\epsilon_0} \int_{V'} \frac{\rho_v}{R} dV'$$

↓ potansiyel

★ Finding vector magnetic potential from current density

$$★ \quad \vec{A} = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}}{R} dV' \quad (\text{Wb/m})$$

magnetic vector potential

A vektör potansiyeli ile C çevresi tarafından sınırlanmış, verilen bir S alanı içinden geçen Magnetic flux

$$\underbrace{\vec{\Phi}}_{\text{magnetic flux}} = \int_S \vec{B} \cdot d\vec{s} \quad (\text{wb}) \Rightarrow \int_S (\nabla \times \vec{A}) \cdot d\vec{s} = \oint_C \vec{A} \cdot d\vec{l}$$

$\underbrace{\hspace{10em}}_{\text{Stoke's theorem}}$

$\underbrace{\hspace{10em}}_{S} \hookrightarrow \vec{B} = \nabla \times \vec{A} \quad \underbrace{\hspace{10em}}_C$

BIOT-SAVART LAW AND APPLICATION

$$\underbrace{\vec{A}}_{\text{magnetic potential}} = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}}{R} dV', \quad \vec{J} dV' = \vec{J} S d\ell' = I d\ell'$$

$\downarrow$
cross sectional area

Bir çok devrede akım taşıyan devrenin neden olduğu manyetik alanın belirlenmesi ile ilgileniriz.

~~★ Kapalı Devredeki~~
~~akı yoğunluğu~~

★ Finding Vector magnetic potential from current in a closed circuit

$$\star A = \frac{\mu_0 I}{4\pi} \oint_C \left(\frac{dl'}{R} \right) \quad (\text{Wb/m})$$

magnetik akı yoğunluğu ise

$$B = \nabla \times A = \nabla \times \left[\frac{\mu_0 I}{4\pi} \oint_C \frac{dl'}{R} \right]$$

↓
baya işlem var burdan sonra kolay gelsin.

★ Kapalı Bir Devredeki akımdan magnetik akı yoğunluğu bulmak için Biot-Savart yasası



$$B = \frac{\mu_0 I}{4\pi} \oint_C \frac{dl' \times \vec{r}}{R^2} \quad (\text{T})$$

$\vec{r} = \frac{\vec{R}}{|\vec{R}|}$

$$\star B = \oint_{C'} dB \quad (T)$$

$$\star dB = \frac{\mu_0 I}{4\pi} \left(\frac{dl' \times \underline{r}}{r^3} \right) \quad (T)$$

'P' noktasında
oluş turduğu
manyetik
alan

$\oint B$ manyetik alanının büyüklüğü

$$dB = \frac{\mu_0 I}{4\pi} \cdot \frac{dl \sin \theta}{r^2}$$